

# Continuous effort on ROS2-based technology proliferation and industry adoption in Asia Pacific



Darryl Lee ROS-Industrial Asia Pacific Consortium Manager 09 Nov 2022



### The ROS-Industrial Membership Ecosystem



A Global Consortium with regional presence:



### **Advanced Remanufacturing Technology Centre (ARTC)**



Leading Public-Private Partnership Research Centre in SE Asia Officially Opened on 28th January 2015

- Mission To Develop and Deploy Advanced Manufacturing Solutions and Upskill Workforce, to Drive Local Industry Competitiveness
- Bridging the gap between Research and Industry
  Co-Create and Value Capture with Industry through the Implementation of Solutions









Technology Readiness Level (TRL) is a scale for determining the maturity of a technology

ARTC was created to drive Public Private Partnerships and for translational R&D with industry

Managed by Managed by

### The ROS-Industrial Asia Pacific Journey towards excellence



ROS

### **ROS-Industrial Asia Pacific Playing Field**



### **ROS-Industrial Asia Pacific Ecosystem Position**



### **ROS-Industrial Asia Pacific Capabilities and Demo Showcase**







Nav2

(Creator: Intel, Samsung, UC San Diego and Locus Robotics)



(Creator: Open Robotics)

**IIIROS2** 



### **ROS2 Native Platform Technology Development**

NANYANG TECHNOLOGICAL UNIVERSITY

#### **Eco-system Collaborative R&D**

- Lower the technology adoption barrier
- Increase the success rate of robotics deployment
- Uplift capabilities of the robotics ecosystem

# Strong Support from both Supply and Demand Sides



### **Key Work-streams**

#### Technologies for Robotic Performance Optimization

- Reduce prototype iterations by testing their robotic systems early for more advanced use cases and conditions.
- Enable end users to evaluate the suitability of robot deployments prior to deployment to avoid long ramp-up times or commissioning
- Achieve full visibility, debottlenecking and system-level performance optimization of RMF deployments

#### Technologies for High Performance Safe Robot Operations

- Enable robots to perform their tasks in the vicinity of humans and obstacles
- Enable robots to perform tasks more quickly in areas with more restricted movement
- Improve performance of mobile manipulators from stop-and-go to manipulate-onthe-move

#### Technologies for Auto-configurable Generic Robotic Workspaces

- Production systems can be setup in significantly shorter time with automatic workspace high-fidelity creation
- Self-correction reduces downtime or production fallout/quality issues over time
- Lower TCO using multiple low-cost sensor improvement to achieve higher precision

#### Technologies for ROS 2 Native Robot Controller

ROS2-based controller customizable for any type of X-DOF robotic applications and robots/peripherals











**IIIROS 2** 

# What we do to be the most committed ecosystem player



#### **Student Bootcamp**



- Over 80 students trained since 2018
- Train future roboticists
- Launched an enhanced bootcamp with both SUTD and SP this year
  - Involve more IHLs
  - A platform for industry organisations to participant in giving back



#### World ROS-I Day





- Uniquely ROS-Industrial
- 24 Hours hackathon 3 Regions
- Resolve open REPs and packages on repo
- An estimated 10 ROS-Industrial engineers participate in the event around the clock

### Developer Meeting

#### Autonomous Exploration in ROS



- Technical presentation on topics relevant to ROS
- Rotation among the 3 regions
- Quarterly basis

These efforts **emphasise** ROS Industrial Asia Pacific's **commitment to proliferate ROS** and anchor its role as one of the **most committed ecosystem players** in open-source Robotics.

### **ROS-Industrial AP went to ROSCon 2022!**









- The largest ROS developer conference comprises technical talks, tutorials and booth showcases
- 800 Participants from 38 Countries
- ROS-Industrial Consortium Asia Pacific demonstrated a multi-robot manipulation system

#### Key Takeaway

- Good community platform for passionate developers to engage and discuss
  - Common challenges & experience
  - Standards & Best Practice
  - Limitation & future of ROS
- Multi-robot arm manipulation & Human-robot collaboration are still technically challenging fields in ROS.
- Increasing demand for standardisation
- A strong need to understand the hesitance of the industry migrating to ROS2





## Thank you!





# © 2022 Advanced Remanufacturing and Technology Centre / ROS-Industrial Consortium Asia Pacific

