

Develop ROS™ applications with Visual Studio Code and Azure

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Our ROS for Windows Journey

Our ROS Journey

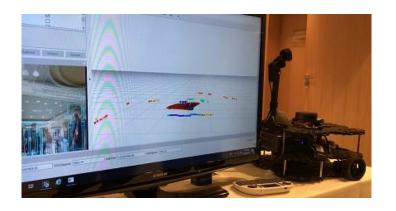
Oct 2019
ROSCON 2019
Developer flow using VS Code and Azure

Jul 2019
Preview of VS Code extension for ROS

May 2019
Microsoft Build 2019
General Availability of ROS on Windows

Sep 2018
ROSCON 2018
Experimental Release of ROS on Windows

Jun 2018





Oct 2019

ROS Community Nodes Manipulation **ROS Core** Mobility Microsoft Nodes

ROS Enablement

Azure IoT Hub Connector ROS node
Azure Kinect ROS Driver
Windows ML Tracker ROS node

Azure IOT_Hub connector

Azure IoT Hub Connector ROS node

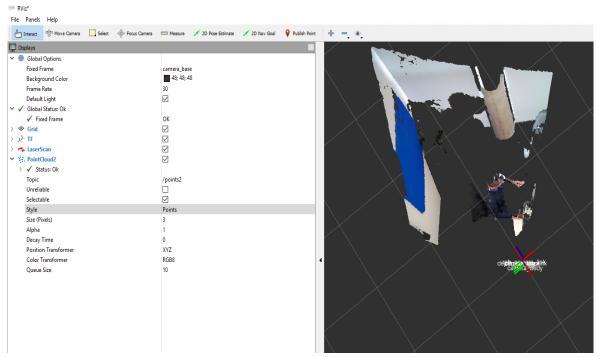
These samples demostrate how to use the various features of Microsoft Azure IoT Hub service to relay telemetry messages or dynamic reconfiguration commands in ROS nodes.

- IOT Hub connector sample in C++
- IOT Hub connector sample in Python
- Dynamic reconfiguration sample

Azure Kinect ROS Node

Azure Kinect ROS Driver

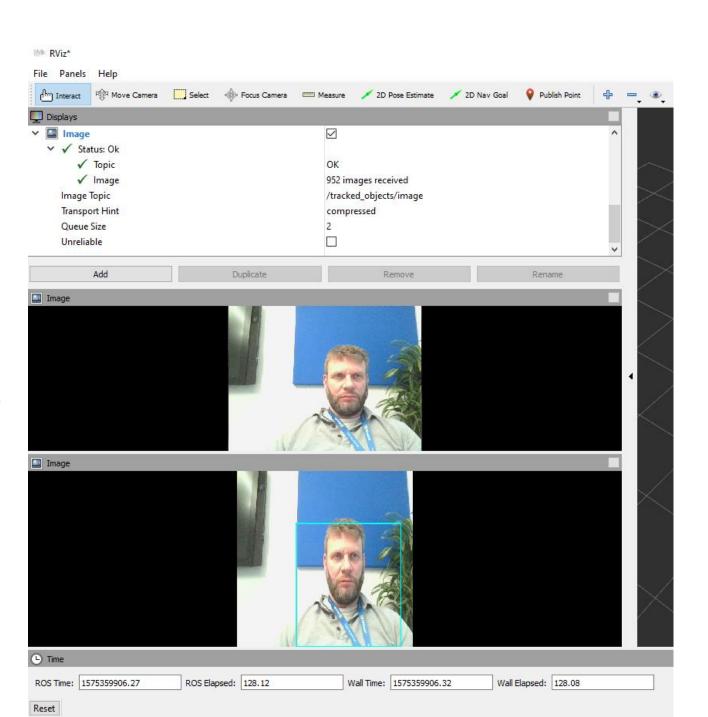
- A PointCloud2, optionally colored using the color camera
- Raw color, depth and infrared Images, including CameraInfo messages containing calibration information
- Rectified depth Images
- Rectified color Images
- The IMU sensor stream
- A TF2 model



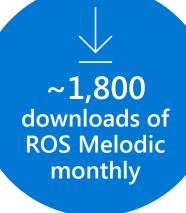
Windows ML Node

Windows ML Tracker ROS node

- ROS node which uses Windows
 Machine Learning (WinML) to
 track people (or other objects)
 in camera frames.
 Uses camera frames from the
 OpenCV based cv_camera node
 at /cv_camera/image_raw
- Outputs an image with the ID boxes for tracked objects overlayed on the source frame at /tracked_objects/image











Visual Studio Code extension for ROS

Visual Studio Code



Free, cross-platform, open source Fast and lightweight Rich extension ecosystem

"In the Stack Overflow 2019 Developer Survey, Visual Studio Code was ranked the most popular developer environment tool, with 50.7% of 87,317 respondents claiming to use it." - Wikipedia

ROS Extension

- Automatic ROS workspace activation.
- Allows starting, stopping and viewing the ROS system status.
- Automatically discover build tasks.
- 3D preview URDF and XACRO files.
- Debug ROS nodes (C++ or Python) by attaching to the process or from the ROS launch.
- And more

URDF Preview

A tool built on top of Robot Web Tools
Visualize URDF\XACRO files in seconds

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ROS2 Support





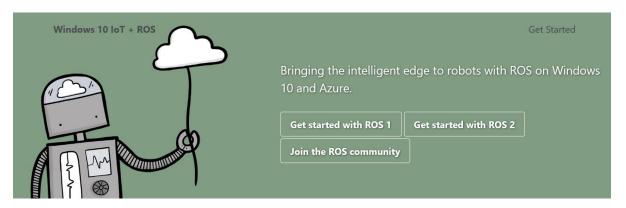




Getting Started

Pre-requisites

Install ROS/ROS2 (Melodic and Dashing) on Windows (http://aka.ms/ros)



Install C\C++ Toolchain (depending on your platform)

GNU GCC on Linux\MacOS

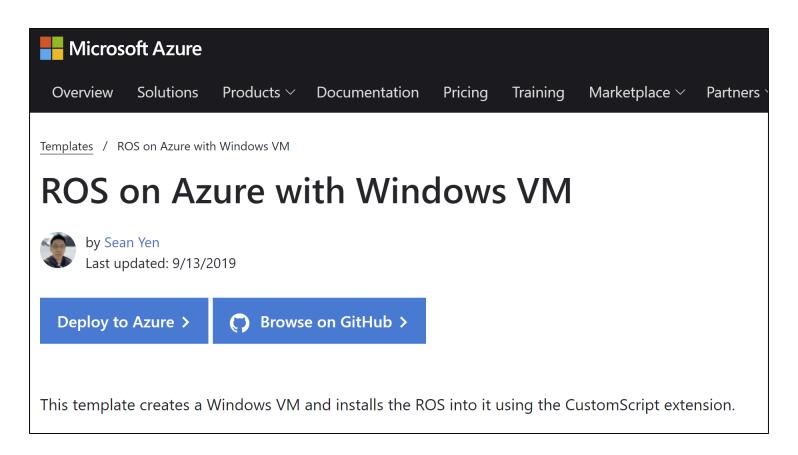
Visual C++ Workload on Windows

Install Visual Studio Code & ROS Extension

ROS on Azure with Windows VM

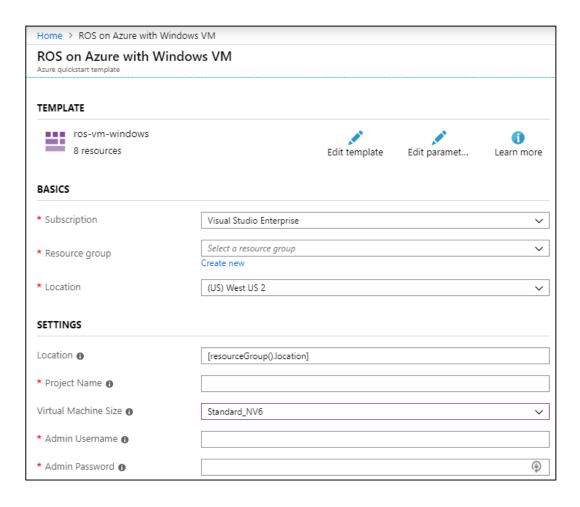
Look for "ROS" on aka.ms/azure/quickstart

(https://azure.microsoft.com/en-us/resources/templates/ros-vm-windows/)



ROS on Azure with Windows VM

Let's walk through the template



What's next?

Add debug support for ROS2 Launch system
Plus ROS and ROS2 coexistence environment
More improvement for cross-platform development
More visualization tooling
End-to-end DevOps workflow

Call to Action

Try it out aka.ms/ros/vscode

Give us feedback on github.com/ms-iot/vscode-ros

Learn more about ROS on Windows IoT and Azure aka.ms/ros

Demo: A simple ROS application

