



# ROS-I Developers' Training

The ROS-Industrial Consortium Americas is providing a three-day [ROS-Industrial Developers Training Class](#) with both Basic and Advanced Track Offerings. The class will run three full days. Please bring a laptop to the class with the ROS-I training Virtual Machine pre-installed. This class is geared toward individuals with a C++ programming background who seek to learn to compose their own ROS nodes. Day 1 will focus on introductory ROS skills/Advanced Topics (Details Below). Day 2 will examine motion planning using MoveIt!, as well as the Descartes planner and perception concepts. Day 3 offers a lab programming exercise with a choice of Pick-and-Place Application, Perception, or Descartes Application.

## Agenda

The ROS-Industrial *Consortium* is a membership organization. Training is free to dues-paying members (limit three seats per Full member, two seats per Associate member, and one seat per Research member ). Others may attend for a fee of \$2,199.

### Class Prerequisites:

Basic understanding of programming (C++ preferred), Ubuntu Linux, and Linux command line. If Linux and C++ are new to you, complete [the prerequisites](#) of the online curriculum for background.

### Event Location:

Southwest Research Institute  
6220 Culebra Rd., San Antonio, TX 78238

### Accommodations:

Courtyard by Marriot SeaWorld/Westover Hills  
11605 TX-151, San Antonio, Texas 78251  
(Block Reserved under ROS-I, Transportation to and from SwRI included!)

### For more information, please contact:

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		Basic	Advanced
Classroom	Day 1	0815 0835-0900 0900-1015 1015-1030 1030-1200 1200-1300 1300-1430 1430-1445 1445-1700	0815 0835-0900 0900-1015 1015-1030 1030-1200 1200-1300 1300-1430 1430-1445 1445-1700
		Depart from the hotel	Depart from the hotel
		Sign-in, Introductions, and Agenda	Sign-in, Introductions, and Agenda
		ROS Setup, Catkin, Installing Packages	Intro to ROS2
		Break	Break
		Creating Packages/Nodes, Topics, Messages	ROS2 build system and operations
		Lunch (Provided) – SwRI Overview Presentation	Lunch (Provided) – SwRI Overview Presentation
		Services, Actions	Porting ROS1 applications to ROS2
		Break	Break
		Launch Files, Parameters	Porting ROS1 applications to ROS2 (cont.)
Classroom	Day 2	1720	ROS1 to ROS2 bridge
		Wrap-up	Wrap-up
		0815 0835-0900 0900-1015 1015-1030 1030-1200 1200-1330 1330-1500 1500-1515 1515-1700 1720	0815 0835-0900 0900-1015 1015-1030 1030-1200 1200-1330 1330-1500 1500-1515 1515-1700 1720
		Depart from the hotel	Depart from the hotel
		Recap and Agenda	Recap and Agenda
		URDF, Workcell XACRO	URDF, Workcell XACRO
		Break	Break
		TF, Build a MoveIt! Package	TF, Build a MoveIt! Package
		Lunch (Provided)	Lunch (Provided)
		Motion Planning Using Rviz, C++	Motion Planning Using Rviz, C++
Lab	Day 3	1500-1515 1515-1700 1720	1500-1515 1515-1700 1720
		Break	Break
		Introduction to Descartes Path Planning and Perception	Introduction to Descartes Path Planning and Perception
		Wrap-up	Wrap-up
		0815 0835-0900 0900-1030 1030-1045 1045-1200 1200-1245 1245-1530	0815 0835-0900 0900-1030 1030-1045 1045-1200 1200-1245 1245-1530
		Depart from the hotel	Depart from the hotel
		Recap and Agenda	Recap and Agenda
		Lab Introduction, Labs	Lab Introduction, Labs
		Break	Break
		Work on Lab Applications	Work on Lab Applications